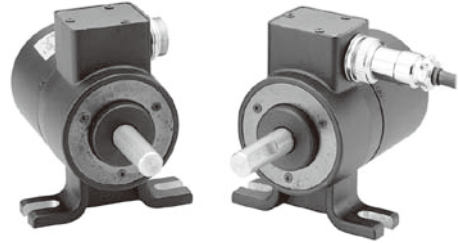


Side-mounting Shaft type Incremental Rotary Encoder

■ Features

- Strong die cast structure against external impact
- Convenient structure for direct mounting on the frame
- Connector type
- Power supply : 5VDC, 12-24VDC ±5%

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

| | | | | | | | | |
|--|---------------------|-------------------------|--|-----------------------------------|---|---|---|----|
| ENA | — | 5000 | — | 2 | — | N | — | 24 |
| Series | Pulse/1Revolution | Output phase | Output | Power supply | | | | |
| Side-mounting shaft type (External diameter of shaft : ϕ 10mm) | Refer to resolution | 2 : A, B 3 : A, B, Z | T : Totem pole output N : NPN open collector output V : Voltage output | 5 : 5VDC ±5% 24 : 12-24VDC ±5% | | | | |

※Standard : ENA--2-N-24

■ Specifications

| | | | |
|-------------------------------|---|---|---|
| Item | Side-mounting shaft type of incremental rotary encoder | | |
| Resolution(P/R) ^{*1} | *1, *2, *5, 10, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000 | | |
| Electrical specification | Output phase | A, B phase(Option : A, B, Z phase) | |
| | Phase difference of output | Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase) | |
| | Control output | Totem pole output | • Low - Load current:Max. 30mA, Residual voltage : Max. 0.4VDC • High - Load current:Max. 10mA, Output voltage(Power voltage 5VDC):Min. (Power voltage-2.0)VDC, Output voltage(Power voltage 12-24VDC):Min. (Power voltage-3.0)VDC |
| | | NPN open collector output | Load current : Max. 30mA, Residual voltage : Max. 0.4VDC |
| | | Voltage output | Load current : Max. 10mA, Residual voltage : Max. 0.4VDC |
| | Response time (Rise/Fall) | Totem pole output | Max. 1 μ s |
| | | NPN open collector output | |
| | | Voltage output | |
| | Max. Response frequency | 300kHz | |
| | Power supply | • 5VDC ±5%(Ripple P-P : Max. 5%) • 12-24VDC ±5%(Ripple P-P : Max. 5%) | |
| Current consumption | Max. 80mA(disconnection of the load) | | |
| Insulation resistance | Min. 100M Ω (at 500VDC megger between all terminals and case) | | |
| Dielectric strength | 750VAC 50/60Hz for 1 minute(Between all terminals and case) | | |
| Connection | Connector type | | |
| Mechanical specification | Starting torque | Max. 70gf·cm(0.007N·m) | |
| | Moment of inertia | Max. 80g·cm ² (8×10 ⁻⁶ kg·m ²) | |
| | Shaft loading | Radial : 10kgf, Thrust : 2.5kgf | |
| | Max. allowable revolution ^{※2} | 5000rpm | |
| Vibration | 1.5mm amplitude or 300m/s ² at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours | | |
| Shock | Approx. Max. 75G | | |
| Environment | Ambient temperature | -10 to 70°C, storage : -25 to 85°C | |
| | Ambient humidity | 35 to 85%RH, storage : 35 to 90%RH | |
| Protection | IP50(IEC standard) | | |
| Cable | ϕ 5, 5-wire, Length : 2m, Shield cable (AWG 24, Core diameter : 0.08mm, Number of cores : 40, Insulator out diameter : ϕ 1) | | |
| Accessory | ϕ 10mm coupling | | |
| Approval | CE | | |
| Unit weight | Approx. 345g | | |

※1: '*' pulse is only for A, B phase

※2: Make sure that. Max response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

$$[\text{Max. response revolution}(\text{rpm})] = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$$

※Environment resistance is rated at no freezing or condensation.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controller

(R) Graphic/Logic panel

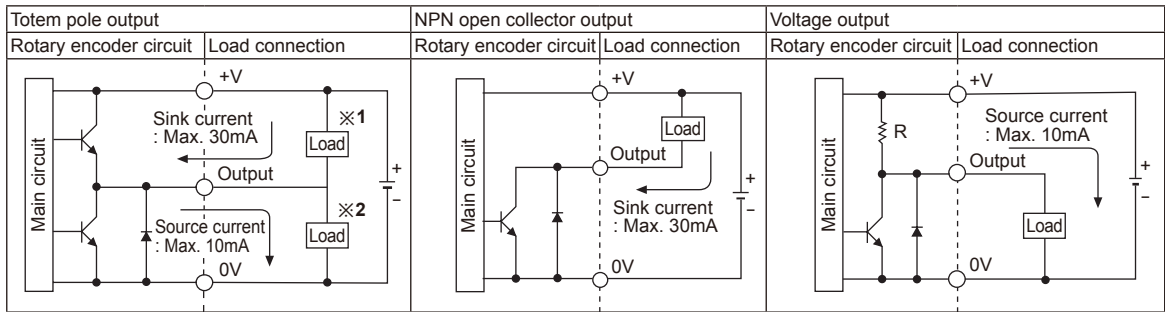
(S) Field network device

(T) Software

(U) Other

ENA Series

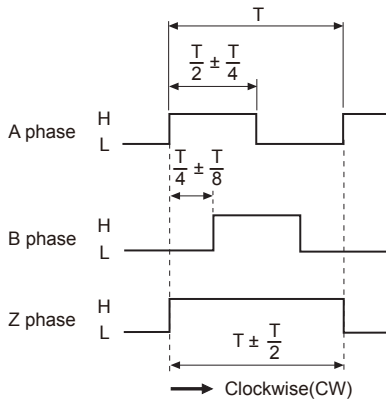
Control output diagram



- The output circuits of A, B phase (Option : A, B, Z phase) are the same.
- Totem pole output type can be used for NPN open collector type(※1) or voltage output type(※2).

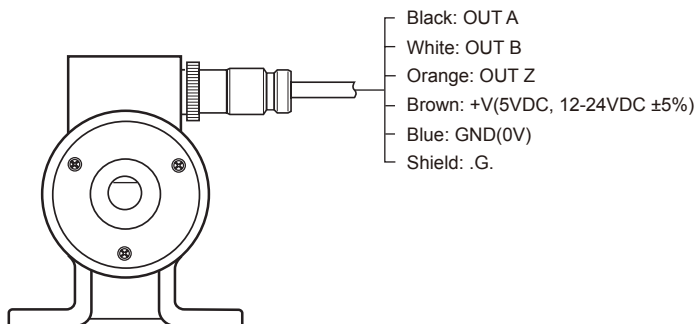
Output waveform

- Totem pole output / NPN open collector output / Voltage output



- ※Z phase output is option.
- ※CW : Right turn as from the shaft

Connections



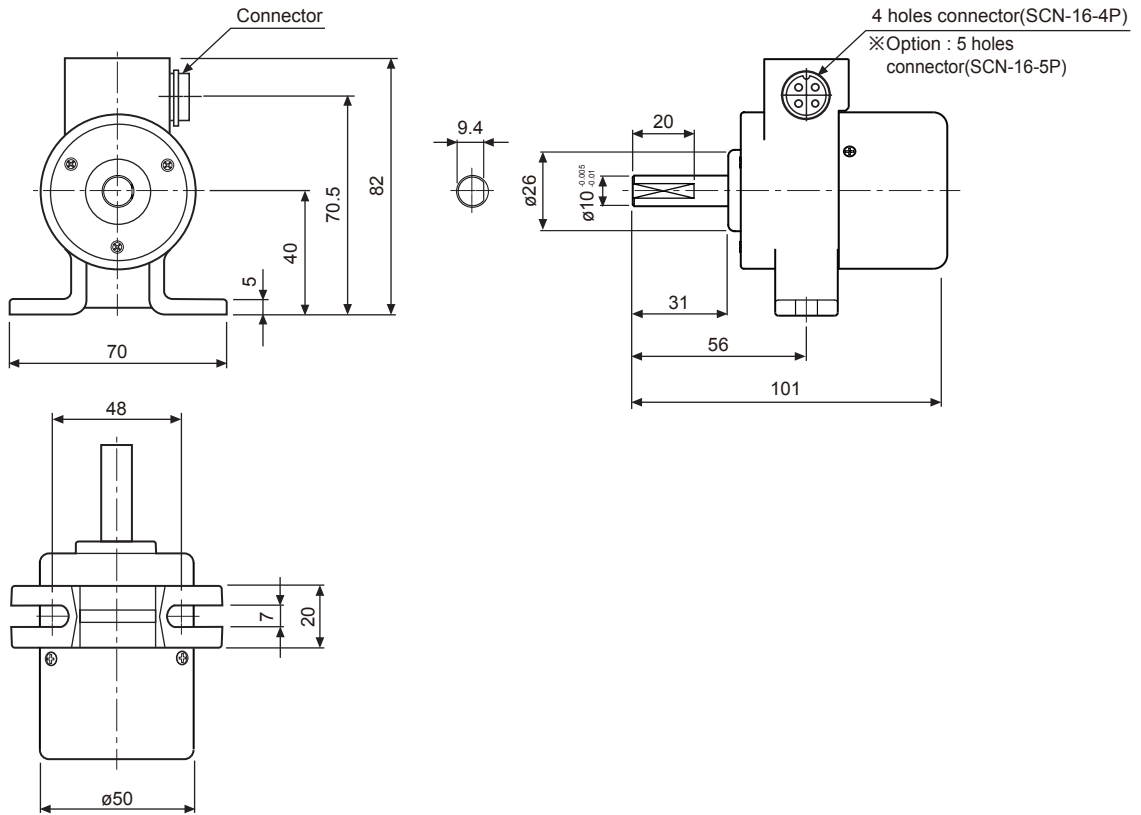
| Pin No | Cable color | Function |
|--------|-------------|----------|
| ① | Black | OUT A |
| ② | White | OUT B |
| ③ | Brown | +V |
| ④ | Blue | GND |
| ⑤ | Blue | GND |

- ※Z phase output is option.
- ※Unused wires must be insulated.
- ※The metal case and shield cable of encoder must be grounded(F.G.).

Incremental Side-Mounting type

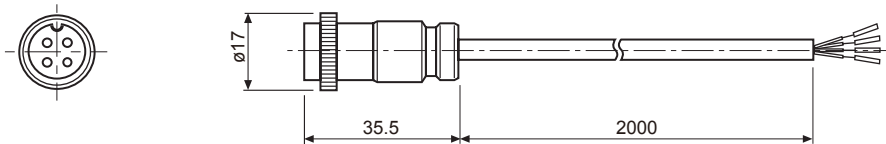
■ Dimensions

(unit: mm)

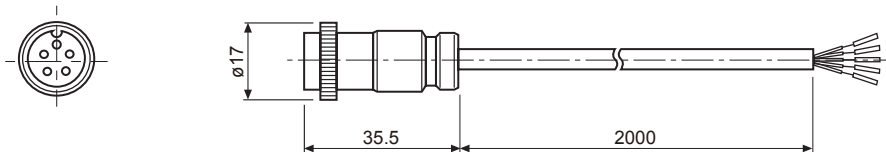


◎ Connector cable

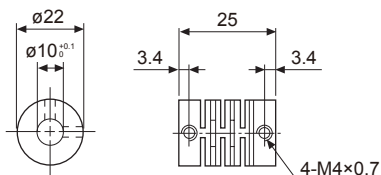
● ENA(2m, 4-wire)



● ENA(2m, 5-wire) (Option)



◎ Coupling(ENA)



- Parallel misalignment : Max. 0.25mm
- Angular misalignment : Max. 5°
- End-play : Max. 0.5mm
- ※For parallel misalignment, angular misalignment, end-play terms, refer to the F-78 page.

| | |
|-----|----------------------------------|
| (A) | Photo electric sensor |
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